

# Constructions of contact structures via the moment map I

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## 1 Introduction

- Contact submanifolds
- Main Theorem

## 2 Constructions via the moment map

## 3 Proof of Main Theorem

- The rough idea
- Perturbation of contact submanifolds

# Contact submanifolds

$(M, \xi)$ ,  $(N, \eta)$ : contact manifolds.

## Definition

An embedding  $f : M \rightarrow N$  is said to be a contact embedding if  $TM \cap \eta|_M = \xi$ . Then  $(M, \xi)$  is called a contact submanifold of  $(N, \eta)$ .

Let  $\xi = \ker \alpha$  and  $\eta = \ker \beta$ .

- $TM \cap \eta|_M = \xi \Leftrightarrow \ker(f^*\beta) = \ker \alpha$ .

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- $(S^3, \eta_0 = \ker f^* \alpha_0)$ ,  $f^* \alpha_0 = r_1^2 d\theta_1 + r_2^2 d\theta_2$ .



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- Since  $TV = JTV$ ,  $TK \cap \xi_0|_K = TK \cap JTK$ .
- $(K, TK \cap \xi_0|_K)$  is a contact submanifold.

# Examples 2-2

**Brieskorn singularity** (Milnor)  $z_1^p + z_2^q + z_3^r = 0$ .

1 Spherical  $\frac{1}{p} + \frac{1}{q} + \frac{1}{r} > 1$ ,

$(2, 2, r)$ :  $A_{r-1} \Rightarrow$  tight str on  $L(r, r-1)$ ,

$(2, 3, 5)$ :  $E_8 \Rightarrow$  tight str on  $\Sigma(2, 3, 5)$ .

2 Euclidean  $\frac{1}{p} + \frac{1}{q} + \frac{1}{r} = 1 \Leftrightarrow$  Simple elliptic sing

3 Hyperbolic  $\frac{1}{p} + \frac{1}{q} + \frac{1}{r} < 1$ ,

$(4, 4, 4)$ :  $S^1$ -bundle over  $\Sigma_3$  with the Euler class  $-4$ .

# Examples 2-3

**Simple elliptic singularity** (Saito, Neumann, cf. Mori)

$$\tilde{E}_6 : z_1^3 + z_2^3 + z_3^3 + \lambda_1 z_1 z_2 z_3 = 0 \quad (\lambda_1^3 + 27 \neq 0),$$

$$\tilde{E}_7 : z_1^2 + z_2^4 + z_3^4 + \lambda_2 z_1 z_2 z_3 = 0 \quad (\lambda_2^4 - 64 \neq 0),$$

$$\tilde{E}_8 : z_1^2 + z_2^3 + z_3^6 + \lambda_3 z_1 z_2 z_3 = 0 \quad (\lambda_3^6 - 432 \neq 0).$$

**Cusp singularity** (Laufer, Hirzebruch, Neumann, K, cf. Mori)

$$T_{pqr} : z_1^p + z_2^q + z_3^r + \lambda z_1 z_2 z_3 = 0 \quad (\lambda \neq 0, \frac{1}{p} + \frac{1}{q} + \frac{1}{r} < 1).$$



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- $(T_A, \ker(\beta_+ + \beta_-)),$  Anosov contact str,

$$A = \begin{pmatrix} p-1 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q-1 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} r-1 & -1 \\ 1 & 0 \end{pmatrix}.$$

# Examples 3

**Via moment polytope of  $S^5$**  (Mori, K, Furukawa)

The followings can be contact submfd's of  $(S^5, \xi_0)$ .

- 1 An overtwisted contact str on  $S^3$ ,
- 2 Tight contact str's on  $T^3$ ,
- 3 Some tight contact str's on  $T^2$  bundles over  $S^1$ .

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  - 3 Some tight contact str's on  $T^2$  bundles over  $S^1$ .
- **The construction of the last ones can also explain the links of simple elliptic and cusp singularities.**

# Main Theorem

## Theorem

*The singularity link of  $f_{m,k}(z) = 0$  is contactomorphic to  $(T_{A_{m,k}}, \ker(\beta_+ + \beta_-))$  if  $k \neq 0$ , and to  $(T_{A_{m,0}}, \ker(dy + mzd x))$  if  $k = 0$ , where*

$$f_{1,(k_1)}(z) = z_1^2 + z_2^3 + z_3^{6+k_1} + z_1 z_2 z_3$$

$$f_{2,(k_1,k_2)}(z) = z_1^2 + z_2^{4+k_1} + z_3^{4+k_2} + z_1 z_2 z_3$$

$$f_{3,(k_1,k_2,k_3)}(z) = z_1^{3+k_1} + z_2^{3+k_2} + z_3^{3+k_3} + z_1 z_2 z_3.$$

# Main Theorem 2

$$A_{m,k} = \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & k_1 \\ 0 & 1 \end{pmatrix} \cdots \begin{pmatrix} 1 & 0 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} 1 & k_m \\ 0 & 1 \end{pmatrix},$$

where  $m \in \mathbb{Z}_{>0}$ ,  $k = (k_1, \dots, k_m) \in (\mathbb{Z}_{\geq 0})^m$ .

- $A_{m,k}$  is a hyperbolic matrix if  $k \neq 0$ ,
- $A_{m,0}$  is a parabolic matrix.

N. Kasuya, The canonical contact structure on the link of a cusp singularity, Tokyo J. Math. Vol. 37, No. 1, 2014, 1-20.

# The moment polytope

$(r_1, \theta_1, r_2, \theta_2, r_3, \theta_3)$ : the polar coordinates.  
 $S^5 = \{r_1^2 + r_2^2 + r_3^2 = 1\} \subset \mathbb{C}^3$ .

$$\phi : S^5 \rightarrow \mathbb{R}^3; (z_1, z_2, z_3) \mapsto (r_1^2, r_2^2, r_3^2)$$

is called the moment map.  $\Delta := \phi(S^5)$  is the moment polytope.

The projection  $\phi$  is  $T^3$ -fibration over  $\text{Int}\Delta$ ,  
 $T^2$ -fibration over edges,  $S^1$ -fibration on vertices.

# The moment polytope 2

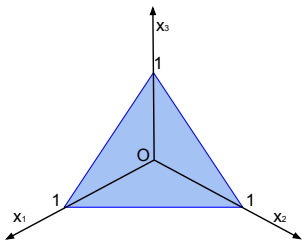


Figure: Moment polytope

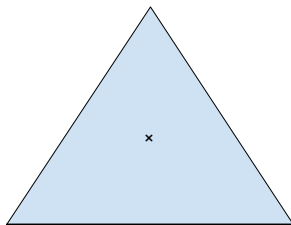


Figure: standard 3-sphere



# The principle

Let  $c : [0, 1] \rightarrow \text{Int}\Delta$  be a curve.  
 $f : T^2 \times [0, 1] \rightarrow S^5$ : an embedding defined by  
**“the slice section”**  $\{p\theta_1 + q\theta_2 + r\theta_3 = 0\}$  over  $c$ .

## Lemma

*$(T^2 \times [0, 1], \ker(f^*\alpha_0))$  is positive contact iff the curve  $c$  rotates (counter) clockwise around the point  $\frac{1}{p+q+r}(p, q, r)$ , when it is inside (outside)  $\Delta$ .*

# Mori's example

A. Mori, The Reeb foliation arises as a family of Legendrian submanifolds at the end of a deformation of the standard  $S^3$  in  $S^5$ , C. R. Acad. Sci. Paris, 350 (2012) 67-70.

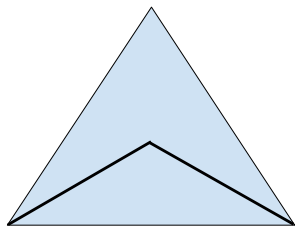


Figure: Reeb foliation

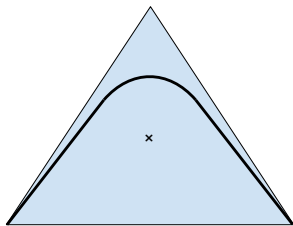


Figure: OT 3-sphere

# The 3-torus case

$(T^3, \eta_n)$ ,  $\beta_n = \sin(2n\pi z)dx + \cos(2n\pi z)dy$ .

We embed  $(T^3, \eta_1)$  in  $(S^5, \xi_0)$  as a contact submfd.  
Define an embedding by

$$f : T^3 \rightarrow S^5; (x, y, z) \mapsto (r_1, r_2, r_3, x, y, -x - y),$$

$$3 \begin{pmatrix} r_1^2 \\ r_2^2 \\ r_3^2 \end{pmatrix} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} + \varepsilon \sin(2\pi z) \begin{pmatrix} 2 \\ -1 \\ -1 \end{pmatrix} + \varepsilon \cos(2\pi z) \begin{pmatrix} -1 \\ 2 \\ -1 \end{pmatrix}.$$

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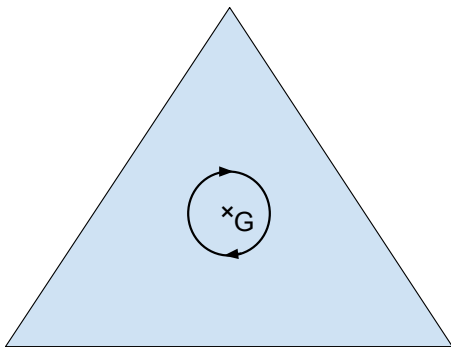
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- $f^*(r_1^2 d\theta_1 + r_2^2 d\theta_2 + r_3^2 d\theta_3) = \varepsilon \beta_1$ .
- $(T^3, \ker f^* \alpha_0) \cong (T^3, \eta_1 = \ker \beta_1)$ .

## The 3-torus case 2

Let us project  $f(T^3)$  by  $\phi$  on  $\Delta$ .

$G = (1/3, 1/3, 1/3)$ : the barycenter of  $\Delta$ .



# The 3-torus case 3

- 1  $l := \phi(f(T^3))$  is a loop around  $G$ .
- 2 The embedding of  $T^3$  is defined by the slice section  $\{\theta_1 + \theta_2 + \theta_3 = 0\}$  over  $l$ .

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  - 2 The embedding of  $T^3$  is defined by the slice section  $\{\theta_1 + \theta_2 + \theta_3 = 0\}$  over  $l$ .
- The contact condition is equivalent to the negativity of the angular momentum of the curve  $l: c(z)$  ( $z \in [0, 1]$ ), around  $G$ .



# The $A_{k-1}$ -singularity link

The link of  $z_1 z_2 - z_3^k = 0$  is  $(L(k, k-1), \xi)$ .  
Furukawa showed this by the following argument.  
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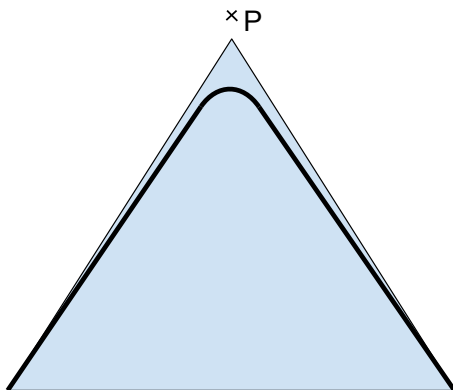
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  - 2 the slice section  $\theta_1 + \theta_2 - k\theta_3 = 0$ .
- Slice sections over  $c([0, \frac{1}{2}])$  and  $c([\frac{1}{2}, 1])$  are the standard contact solid tori pasted by the linear map  $\begin{pmatrix} k & -1 \\ 1 & 0 \end{pmatrix} \Rightarrow (L(k, k-1), \xi)$ .

# The $A_{k-1}$ -singularity link 2



## Some $T^2$ bundles over $S^1$

Let  $A = \begin{pmatrix} p-1 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} q-1 & -1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} r-1 & -1 \\ 1 & 0 \end{pmatrix}$ .

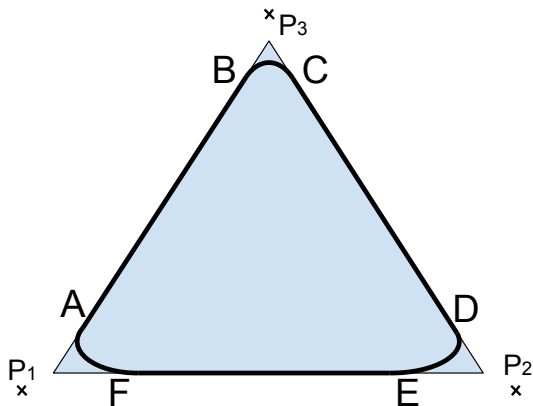
Furukawa embedded  $(T_A, \ker(\beta_+ + \beta_-))$  in  $(S^5, \xi_0)$ .

The slice section over the curve  $c : [0, 1] \rightarrow \Delta$  is defined by

$$\begin{cases} \{(r-1)\theta_3 - \theta_1 - \theta_2 = 0\} (t \in (\frac{1}{6}, \frac{1}{3})), \\ \{(q-1)\theta_2 - \theta_3 - \theta_1 = 0\} (t \in (\frac{1}{2}, \frac{2}{3})), \\ \{(p-1)\theta_1 - \theta_2 - \theta_3 = 0\} (t \in (\frac{5}{6}, 1)). \end{cases}$$

This is also valid for the case  $\frac{1}{p} + \frac{1}{q} + \frac{1}{r} = 1$ .

# Some $T^2$ bundles over $S^1$ 2



# The rough idea

Let  $L_\lambda = S^5 \cap \{z_1^p + z_2^q + z_3^r - \lambda z_1 z_2 z_3 = 0\}$ .  
When  $\lambda \rightarrow \infty$ ,  $\phi(L_\lambda)$  approaches to  $\partial\Delta$ .



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- 1  $L_\lambda$  is approximated by  $z_1 z_2 z_3 = 0$ .
- 2 Near the vertices, it is approximated by  $z_3^{r-1} = \lambda z_1 z_2$ ,  $z_2^{q-1} = \lambda z_1 z_3$ , and  $z_1^{p-1} = \lambda z_2 z_3$ .

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- Namely, we obtained Furukawa's model.

$$L_\lambda \cong \begin{cases} (T_A, \ker(\beta_+ + \beta_-)) & \left(\frac{1}{p} + \frac{1}{q} + \frac{1}{r} < 1\right) \\ (T_A, \ker(dy + mzd x)) & \left(\frac{1}{p} + \frac{1}{q} + \frac{1}{r} = 1\right). \end{cases}$$

# The perturbation

To prove Main Theorem, we construct an isotopy of contact submanifolds between  $L_\lambda$  and Furukawa's model for large  $\lambda$ . Then, by Gray stability, they are contactomorphic. Let  $\varphi : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}$  be a bump function supported on  $\{s \in \mathbb{R} \mid 1 - 2\delta \leq s\}$  and  $\varphi \equiv 1$  on  $\{s \in \mathbb{R} \mid 1 - \delta \leq s\}$  with  $0 < \delta < \frac{1}{5}$ .

$$F_\lambda := z_1 z_2 z_3 - \frac{1}{\lambda} (z_1^p + z_2^q + z_3^r) \text{ and}$$

$$G_\lambda := z_1 z_2 z_3 - \frac{1}{\lambda} (\varphi(r_1^2) z_1^p + \varphi(r_2^2) z_2^q + \varphi(r_3^2) z_3^r).$$

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$$H_t := (1 - t)F_\lambda + tG_\lambda.$$

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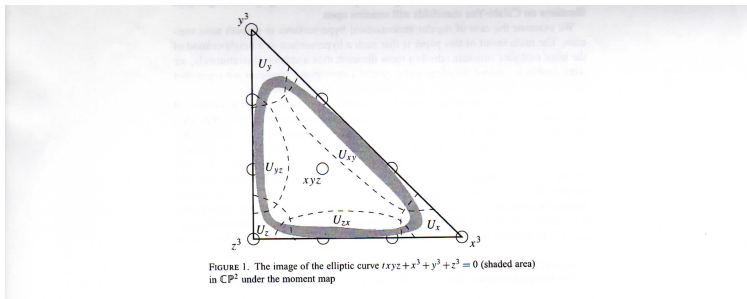
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- 2 On  $\{|z_1|, |z_2|, |z_3| < \sqrt{1 - \frac{1}{2}\delta}\}$ ,  $H_t^{-1}(0)$  is close to  $\{z_1 z_2 z_3 = 0\}$  in the sense of  $C^\infty$  topology, and the contactness is an open condition.

This completes the proof.

# Remark

I. Zharkov used a similar argument to construct Lagrangian torus fibrations of Calabi-Yau hypersurfaces. The figure below represents the elliptic curve  $x^3 + y^3 + z^3 + txyz = 0$  in  $\mathbb{C}P^2$ .  
 I. Zharkov, Torus fibrations of Calabi-Yau hypersurfaces in toric varieties, Duke Math. J. Vol. 101, No. 2, 2000, 237-257.





# Thank you for your attention!